

Cooperation with  
the UN, here from  
meeting with  
UNOOSA in  
Vienna  
2024





Investment hunting  
on  
Norwegian Embassy  
2024





Swedish  
The embassy in  
Washington



# Kunskapsnav Digitalisering

Knowledge hub for  
agricultural digitalization



Europeiska jordbruksfonden för  
landbyggsutveckling, Europeiska  
investitionsfundsprogrammet



Jordbruks  
verket





Kick-off  
23 October





# Goals for the digitalization hub



The knowledge hub's goal is to increase knowledge, strengthen cooperation regarding digitization with relevant actors and for more farmers to see the possibility of using digital equipment. This is with the aim of strengthening the competitiveness of Sweden's primary producers.

The goal of increasing knowledge must be aimed at everyone, regardless of previous knowledge level (digital maturity and use).

By fulfilling the knowledge hub's objectives, the effect is expected to be a stronger agrarian knowledge system that contributes to efficient, profitable and sustainable primary production and a competitive food chain







2 Million Euro, first 3 years





**LUDVIG & CO**



**Sweden Secure  
Tech Hub**



**LINKÖPING  
SCIENCE  
PARK**

**RI.  
SE**



**Agtech  
Sweden**



Medfinansieras av  
Europeiska unionen



**Jordbruksverket**





Professors  
Sofia Nyström  
Per Andersson





# Environmental monitoring





Foto: John Deere, Foderteknik, Agtech Sweden

Milk  
Sustainability  
Center  
Deere +  
DeLaval



## Gårdslaboratorium för jordanalyser

Namn på produkt eller koncept: Radicle Agronomics

Företag eller annan aktör: Precision Planting LLC

Kategori: Växtodling, digitalt stöd för jordprovtagning

### Beskrivning

Radicle Agronomics är ett automatiskt system för jordprovtagning och analys av jordprover. Jorden hämtas upp manuellt av person körandes på t.ex. en fyrhjuling och placeras i runda plastbehållare försedda med RFID-tag genom en speciell utrustning monterad på fyrhjulingen. Behållarna förses med koordinater automatiskt. Inga etiketter eller hantering av provtagningspåsar eller pappersboxar behövs. I ett mobilt jordlaboratorium på bara 3x3 meter, som har namnet Radicle Lab, slutförs sedan analyserna, helt automatiskt. Förutom P, K och pH klarar labbet även magnesium, kalcium, katjonbyteskapacitet (CEC) och basmättnadsnivå (base saturation level). Kväve däremot ingår inte. Den molnbaserade programvaran integrerar provtagning, kartläggning och analys i en enda plattform. Målgruppen uppges vara agronomer som vill leverera bättre rekommendationer för näringshantering liksom slutanvändare, lantbrukare. Kapaciteten är 200 prov per dag. Affärsmodellen är en kombination av leasing (\$13 000 USD per år) och kostnad per prov (\$5,50). Konceptet testades 2022 och presenterades på Agritechnica 2023. Ännu finns ingen i Sverige som testat konceptet. Kvaliteten på analyserna är ännu okända men företaget säger att de har metoder för kalibrering och påtalar att kvalitet också handlar om att ta många prov och gärna oftare än vad fallet brukar vara med vanlig jordprovtagning. Precision Planting har sitt säte i Tremont, Illinois, USA.



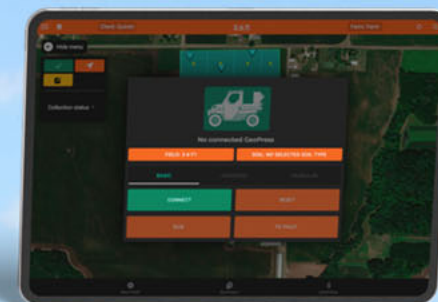
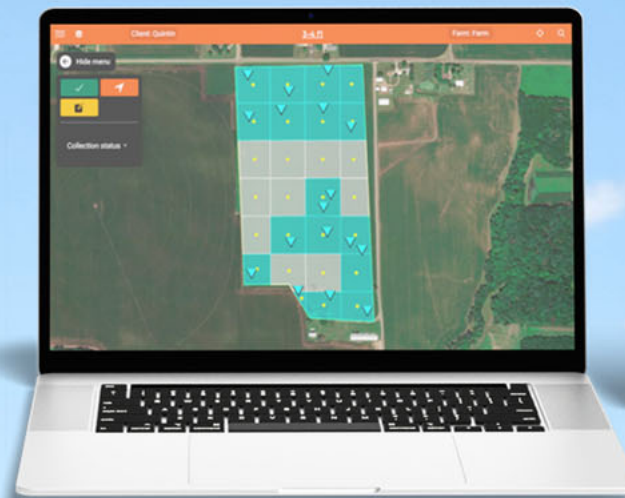
Det mobila laboratoriet som kallas Radicle Lab. Foto: Per Frankelius.

### Källor

<https://www.precisionplanting.com/radicle-agronomics-by-precision-planting>

### Observatör

Per Frankelius, Linköpings universitet, per.frankelius@liu.se







# Need analysis

(ethnographies through for example farm visits)









# Test and evaluation of new technology





Membrane



Ultrasonic



Paddle



Electronic nose











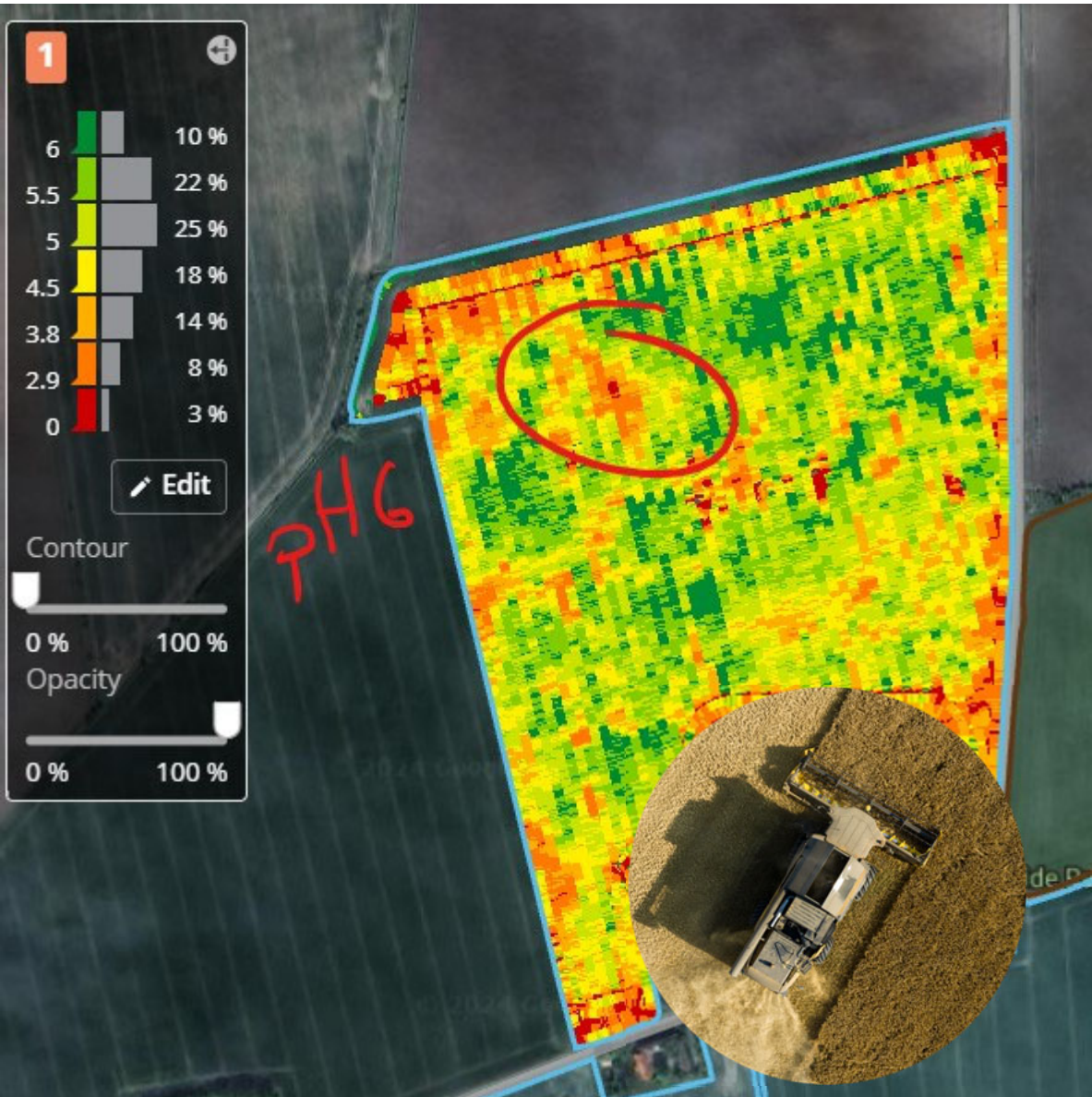
149 0100 00005349  
111111 0111

 nedap  
SmartTag





# User reports

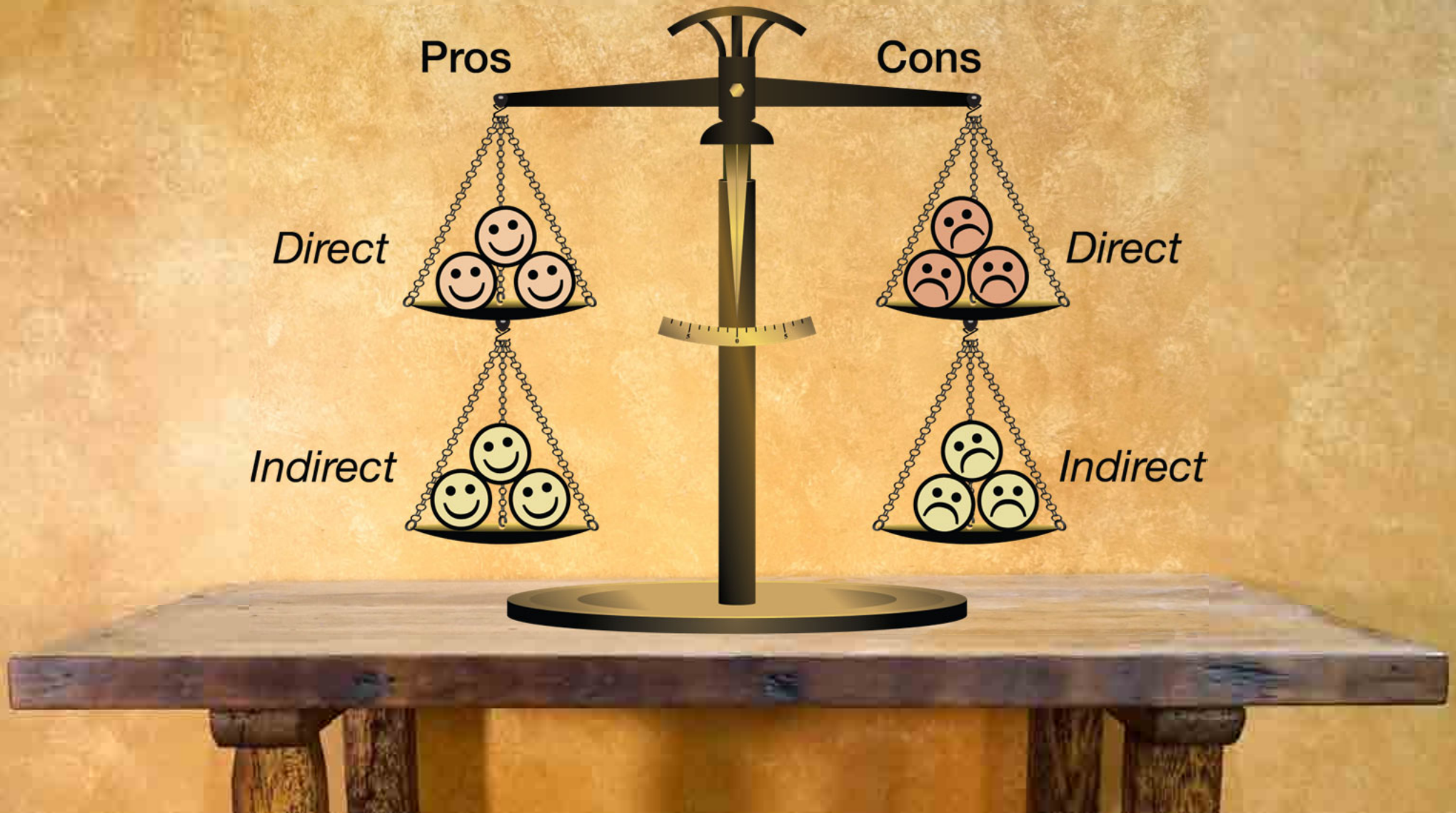


”En inte helt oväntad fördel är att kunna titta på punkter med lågt pH och se om det verkligen är så illa att ha pH 6 på en ensam punkt och resten är pH 6,5-7. Vi vet teoretiskt att det är så men när det också syns direkt i skördekartan att ja, här var det mätbar skördesänkning

Mårten Svensson, Sjöstorps Bygård, Lund









# Trade fairs in focus





Borgeby  
26-27 June









Elmia Lantbruk  
16-18 oktober





Elmia Lantbruk  
16-18 oktober





**EuroTier**  
10th in animal farming

e-National  
100% digital

Inboast-farming



**DLG Pressestelle  
im Convention Center  
DLG Press Office  
in Convention Center**

[eurotier.com](http://eurotier.com) | [energy-decentral.com](http://energy-decentral.com) | [inboast-farming.com](http://inboast-farming.com)



**EuroTier**  
11-14  
november









# Conclusion



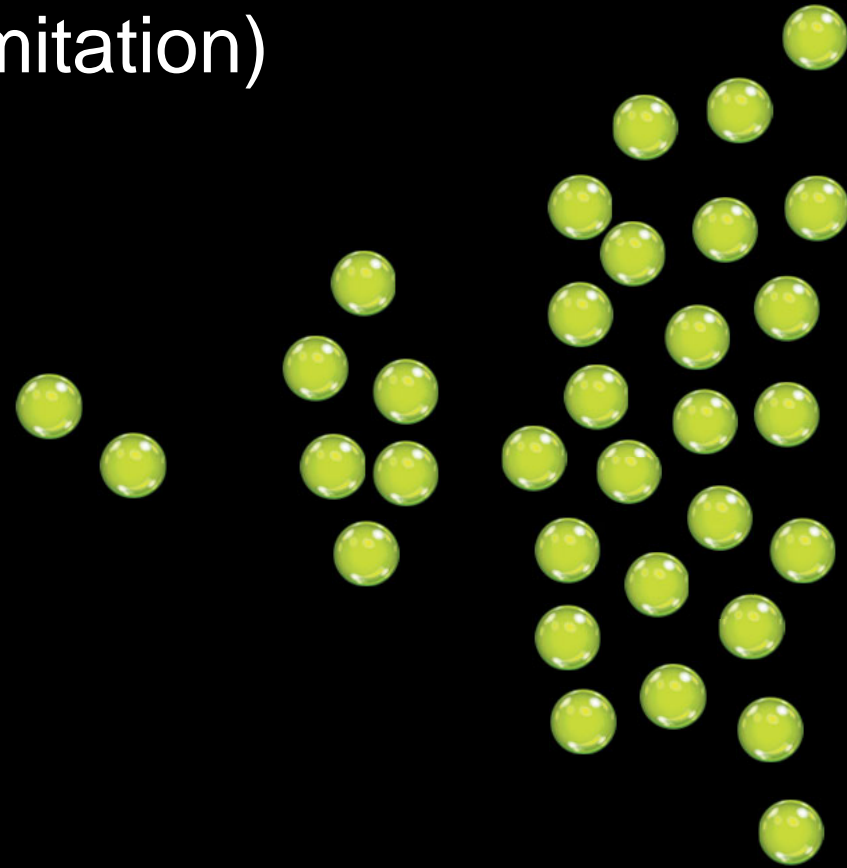
# 1 Responsible innovation





## 2 Responsible diffusion (imitation)

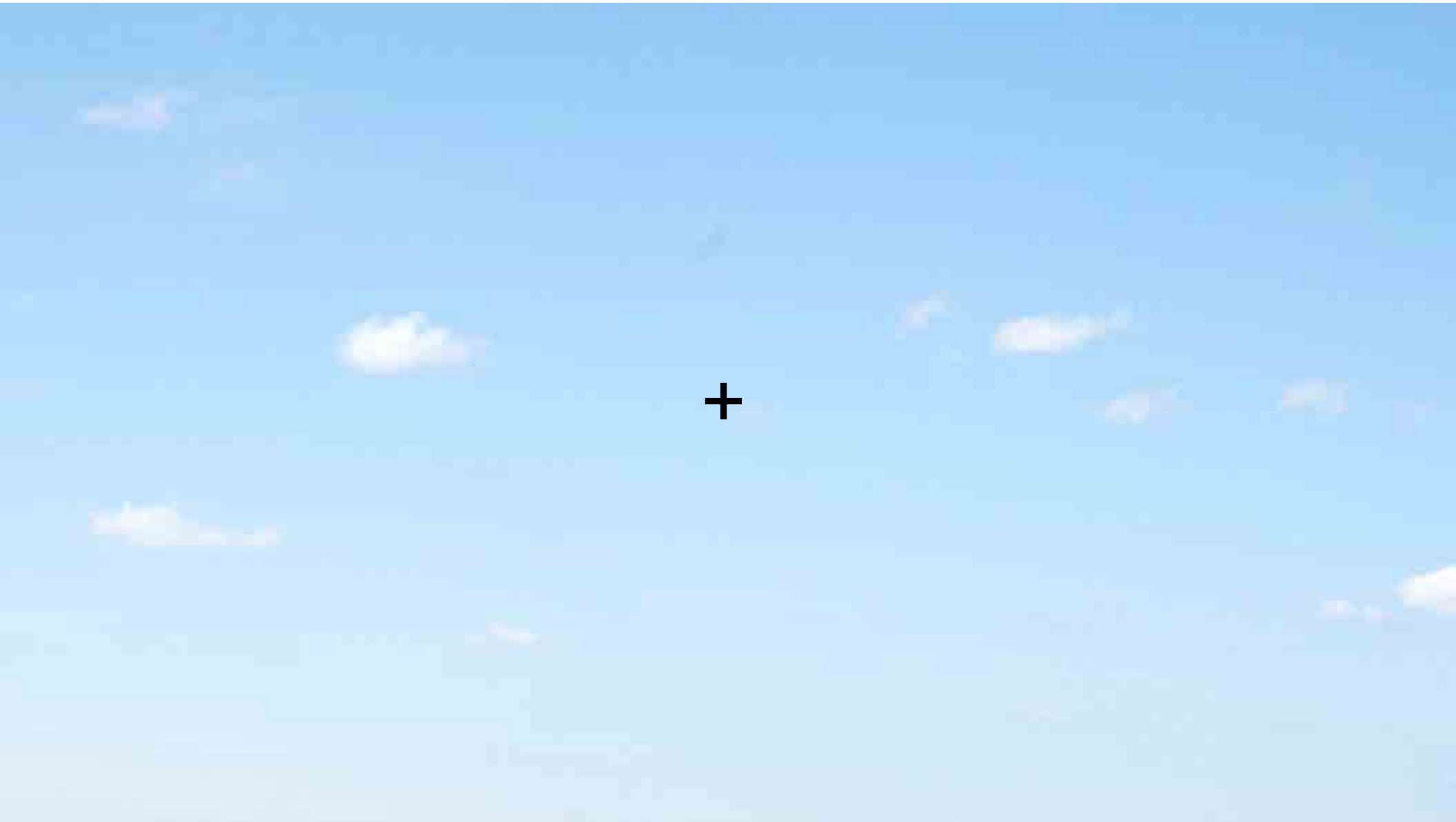
+





Herbert  
Simon  
1978





We need an investment in **pedagogy**  
to stimulate the spread of  
innovative concepts



# Thanks!

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[karolina.muhrman@liu.se](mailto:karolina.muhrman@liu.se)

[www.digitaliseringsnavet.se](http://www.digitaliseringsnavet.se)



Europeiska jordbruksfonden för  
landbruksutveckling. Europas  
investering i landsbygdsområden



Jordbruks  
verket

## References:

### **Need for innovation**

Draghi, Mario (2024). The future of European competitiveness: Part A, A competitiveness strategy for Europe, European Commission, September 2024

### **Imitation and diffusion**

Tarde, G. (1903). The Laws of Imitation. New York: Holt.

### **Innovation**

Schumpeter, J. (1911/1934). The Theory of Economic Development. Oxford: Oxford University

### **Need for external information**

Aguilar F.J. (1967) Scanning the Business Environment. New York: Macmillan.

Simon, H. (1945) Administrative Behavior. New York: Macmillan.

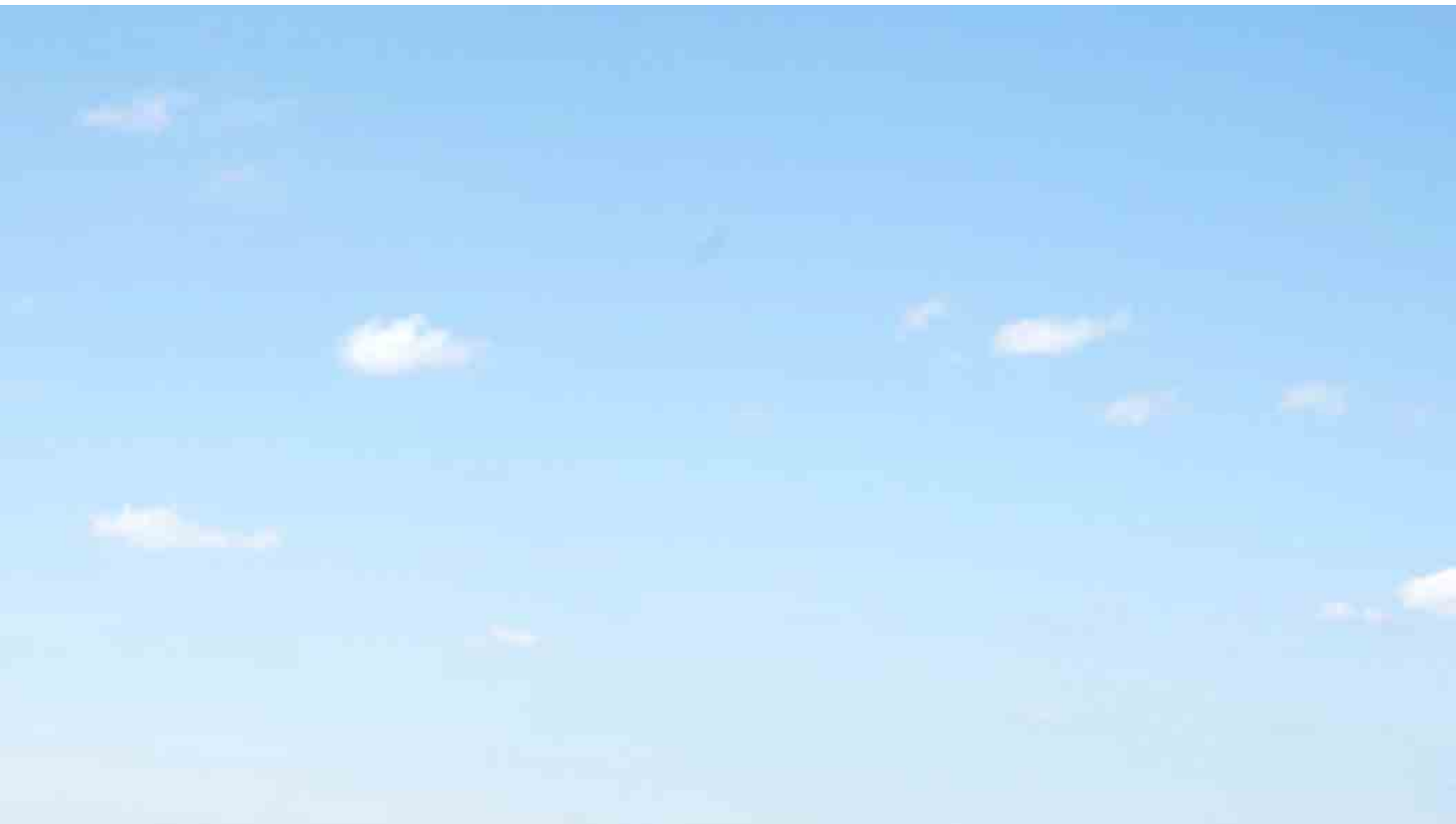
Frankelius, P. (2009) Simon's theorem reconsidered – towards a theoretical framework for competitive intelligence. The Third European Competitive Intelligence Symposium, June 1–12.

### **Need for pedagogy**

Muhrman, K. (2016). Inget klöver utan matematik. En studie av matematik i yrkesutbildning och yrkesliv. (Diss). Linköpings universitet: Institutionen för beteendevetenskap och lärande.

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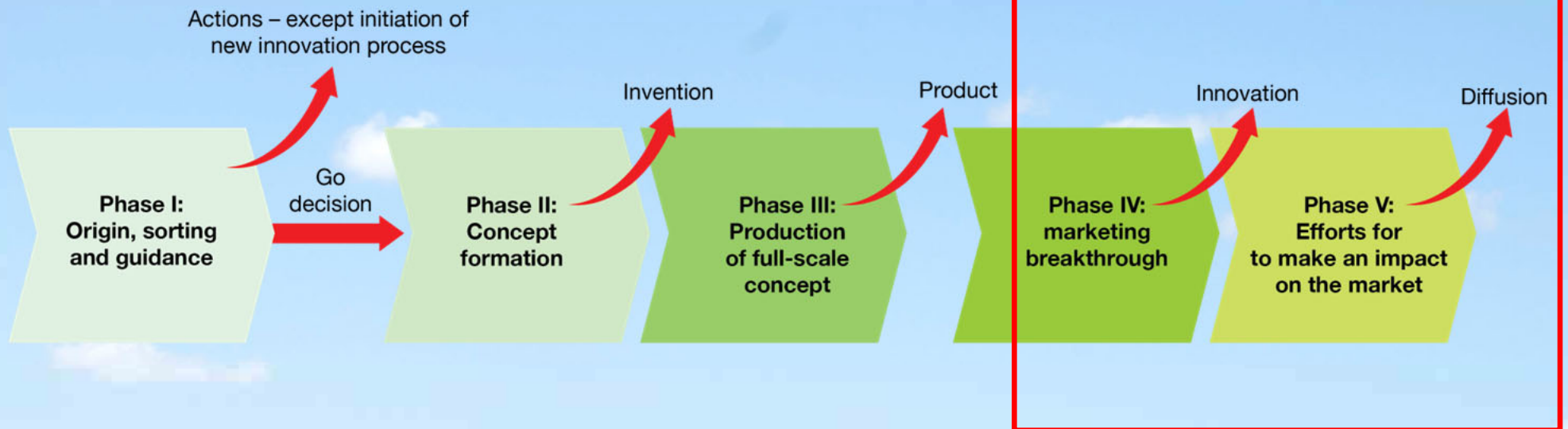


A background image of a clear blue sky with several small, white, fluffy clouds scattered across it. The text 'Summing up' is centered in the middle of the image.

Summing up



## Knowledge hub for agricultural digitalization





Schweizerische Eidgenossenschaft  
Confédération suisse  
Confederazione Svizzera  
Confederaziun svizra

Eidgenössisches Departement für  
Wirtschaft, Bildung und Forschung WBF

Agroscope

# UAV sprayers in Switzerland



Image: S. Rüttimann

Thomas Anken, Agroscope Tänikon, 8356 Ettenhausen, [thomas.anken@agroscope.admin.ch](mailto:thomas.anken@agroscope.admin.ch)





# Use of UAV sprayers in Switzerland



Quick technical development since 2015

Up to 100 kg weight, 45 lt tank for spray liquid  
→ typically 100 l/ha spray liquid

- **100 UAV** sprayers homologated since 2019
- Use mainly in **wineyards** 900 ha of wines
- Quick development for distribution of **slug pellets** in crops
- Surfaces sprayed by **helicopters** decreased since from 1500 ha to 900 ha/year
- Each type of UAV needs to be homologated and each UAV passes a **sprayer test** all 3 years



# Regulation in Switzerland

## Weather conditions

No icing conditions (5 °C and visible moisture)

🌡️ preferably  $\leq 25$  °C in the shade

🌬️  $\leq 5$  m/s (gusts)

👁️  $\geq 1$  km

## UAV pilot / operator of plant protection products

Must be aware of the risks, the relevant processes and contingency plans, UAV in direct sight; *complies with the conditions and instructions for use, proficient in handling plant protection products*



## Treatment parameters

*Flight height for treatments usually  $\leq 6$  m, treatments generally in the autopilot mode, only authorized plant protection products may be applied*



## Civil and military aviation

Give way to manned aircrafts, further restrictions if airport at  $< 5$  km, coordinate UAV spraying with helicopter-based treatments

**No bystanders within the overflow area**



## Legal frame:

<https://www.bazl.admin.ch/bazl/en/home/drohnen/specific/spraying.html>





# Homologation of spray drones

## Testing criterias for the homologation

- spray system fulfils principles of ISO 16122
- transversal distribution of spray liquid: coefficient of variation < 15 %
- accuracy of automated flight route: +/- 50 cm

## Max. lateral windspeed (check for drift reduction):

Distance from UAV	Height above soil	wind speed
10 m	1 m	5 m/s
	2 m	3 m/s
20 m	1 m	3 m/s
	2 m	2 m/s



# Sprayer test: Control of spray system (ISO 16122)



## Standard checks of the spray system like:

filters available, dripping of nozzles after stop of spraying, nozzle flow, flow or pressure indication, leakages, weights...





# Sprayer test: Transversal distribution of spray liquid

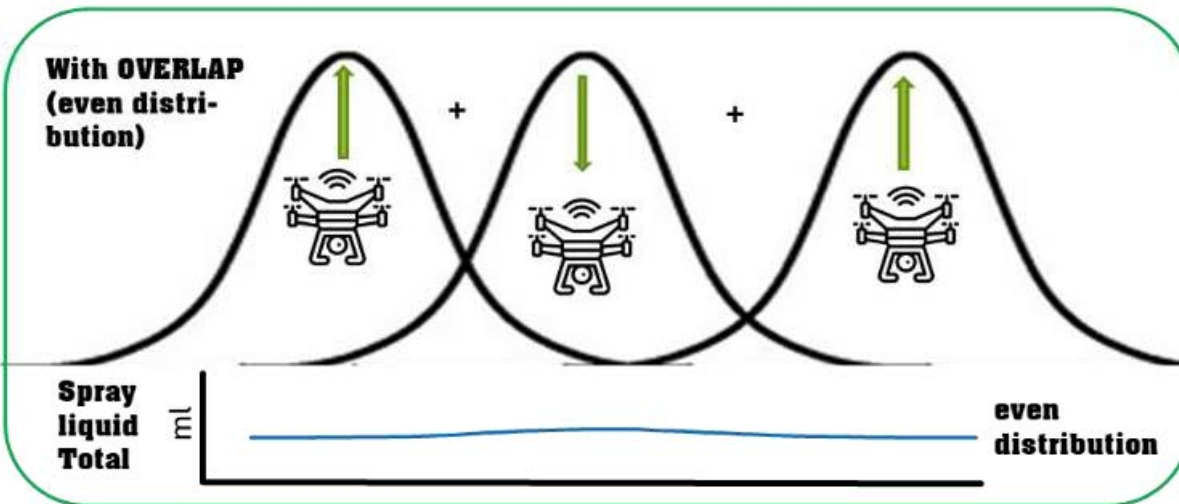
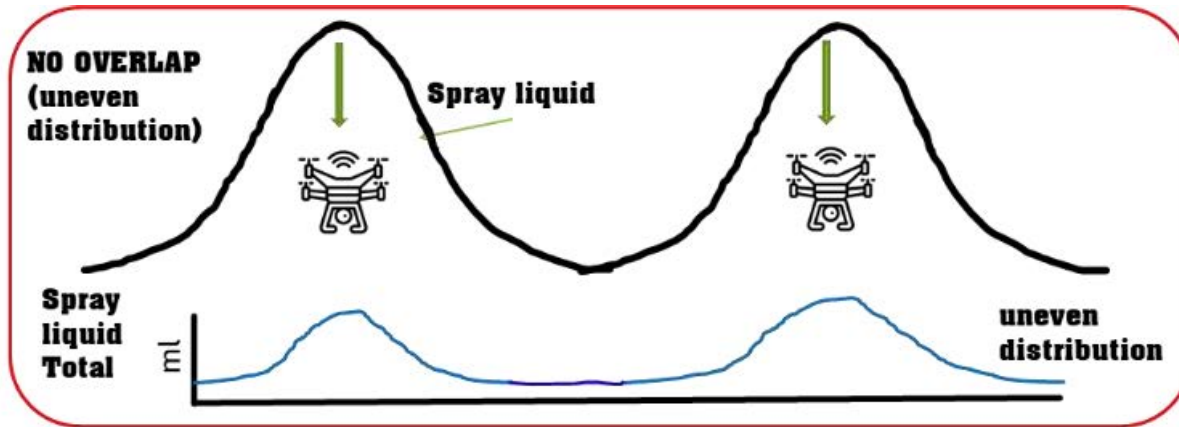


Patternator (6 m x 3 m, same principle as the ones for field sprayers)

- UAV is hovering at the same place over the patternator
- lateral wind is strongly influencing the distribution
- flying height 2.5 m

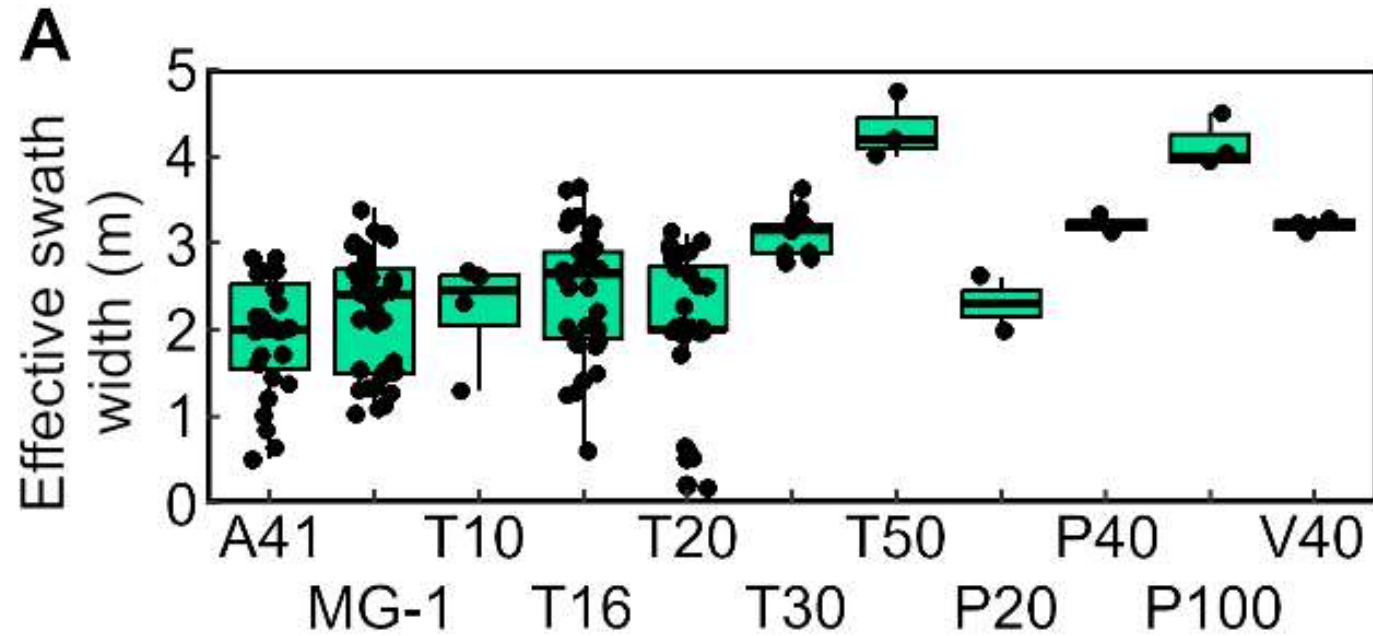


# Regular distribution needs overlap of the swathes





# Swath widths are smaller than indicated by the manufacturers



drone width and take-off weight determine the swath width  
→ a UAV with a width of 3 m will not spray 10 m

# Comparison of 3 methods to measure transversal distribution



patternator



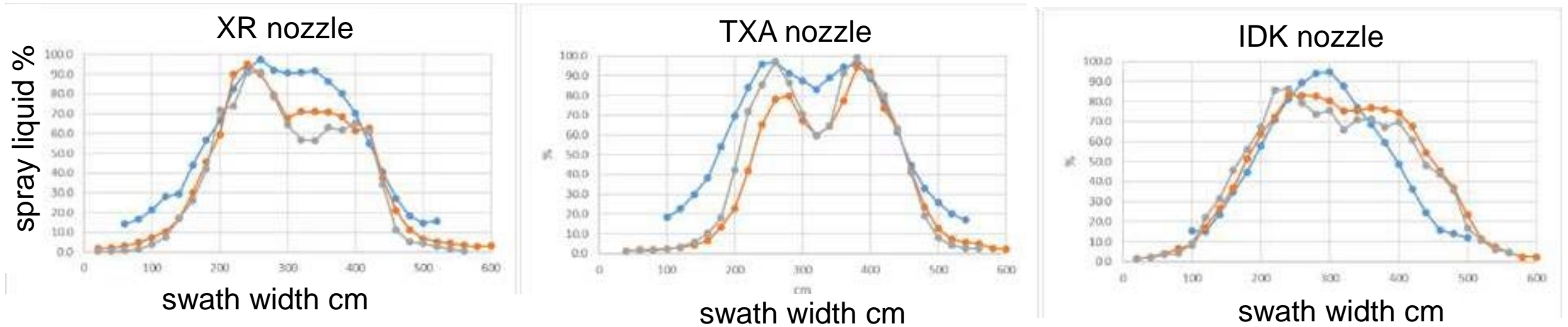
tracer/ water  
sensitive paper



- tracer and photometric analysis
- water sensitive paper: treated surface determined by computer vision (in collaboration with Syngenta)



# Transversal distribution of different nozzles & test methods



patternator tracer water sensitive paper

- Teejet XR (flat fan) & TXA (hollow cone), Lechler IDK (flat fan air injection) (Drone DJI T16)
- «water goes where the wind blows» → no significant influence of nozzles
- no significant differences between different methods

(Anken et al. 2024)



# Homologation: Measuring wind speed

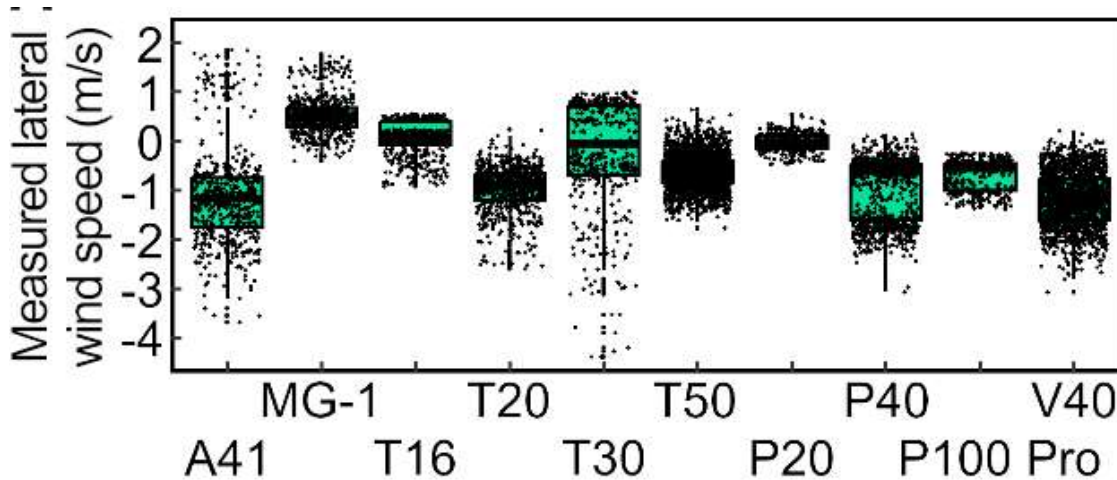


three dimensional ultrasonic sensors allow the measurement in three directions (10 Hz)

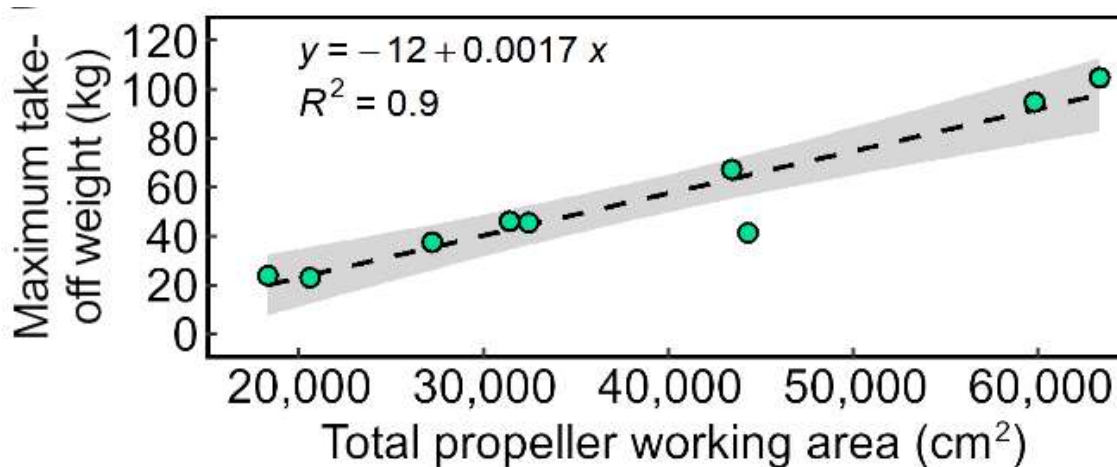


# Wind speeds and take off weight of homologated drones

wind speed at 10 m distance 1 m height



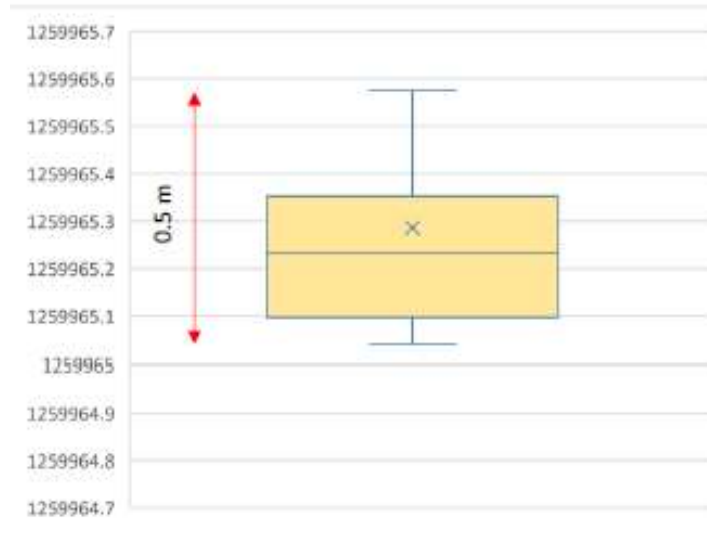
→ lateral wind speeds show little variation across different models



→ larger propellers not higher revolutions carry the supplementary weight  
→ we assume this to be the explanation for the quite low wind speeds



# Homologation: Accuracy of flight route



achieved accuracies in general:

- values are within 0.5 m
- 50 % of values +/- 10 cm

UAV is flying along a defined route simulating a field

RTK-GNSS data logger to measure the deviation

RTK logger

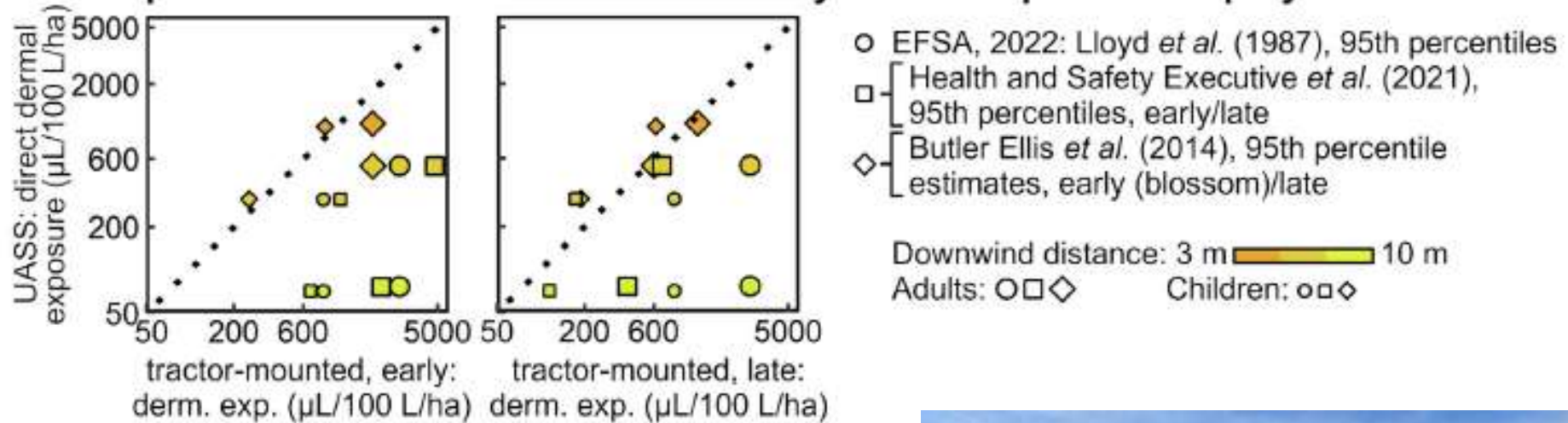






# Drift and bystander measurements

**B tractor-mounted spraying equipment vs. UASS:  
potential direct dermal resident and bystander exposure to spray drift**



(Dubuis *et al.* 2023)

→ spray drift of drones is lower than standard tractor mounted air blast sprayers

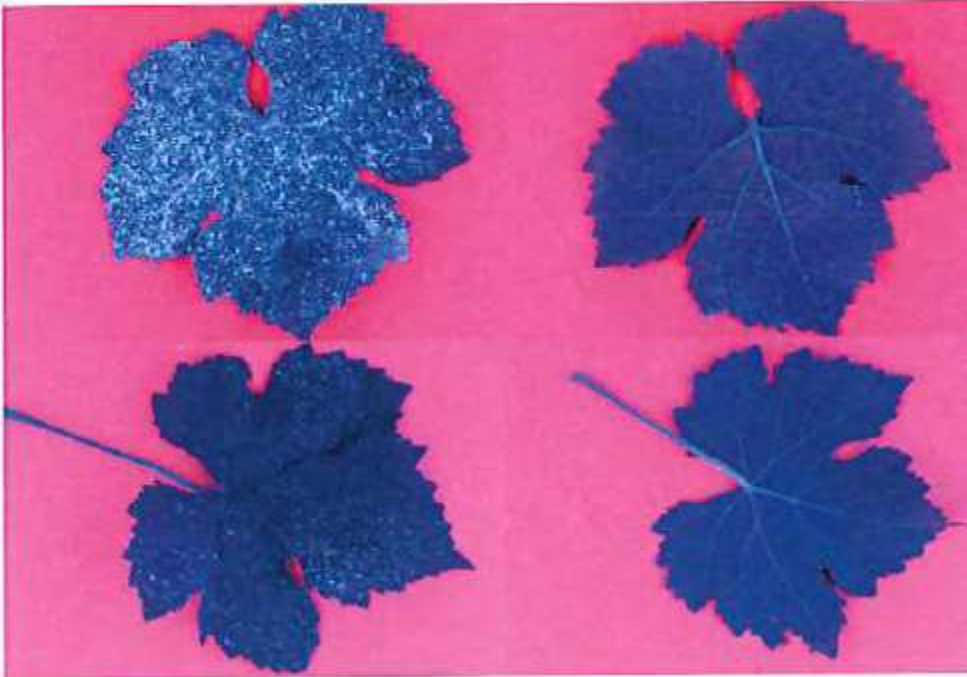




# Efficacy of the treatment on vine

leave upside

leave underside



top of plant

bottom

downsides of leaves and bottom of plants and bunches are not well treated

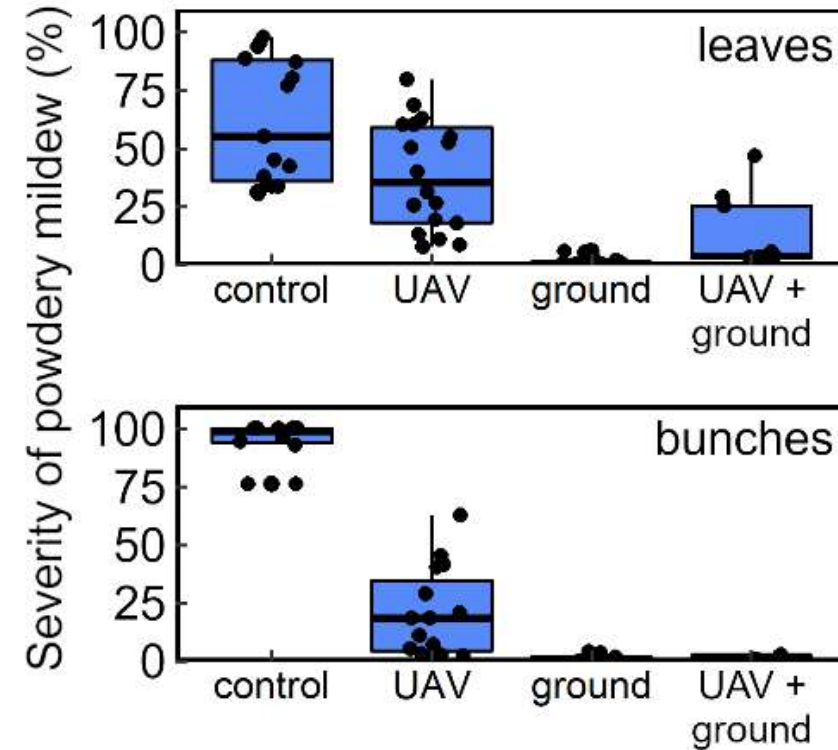
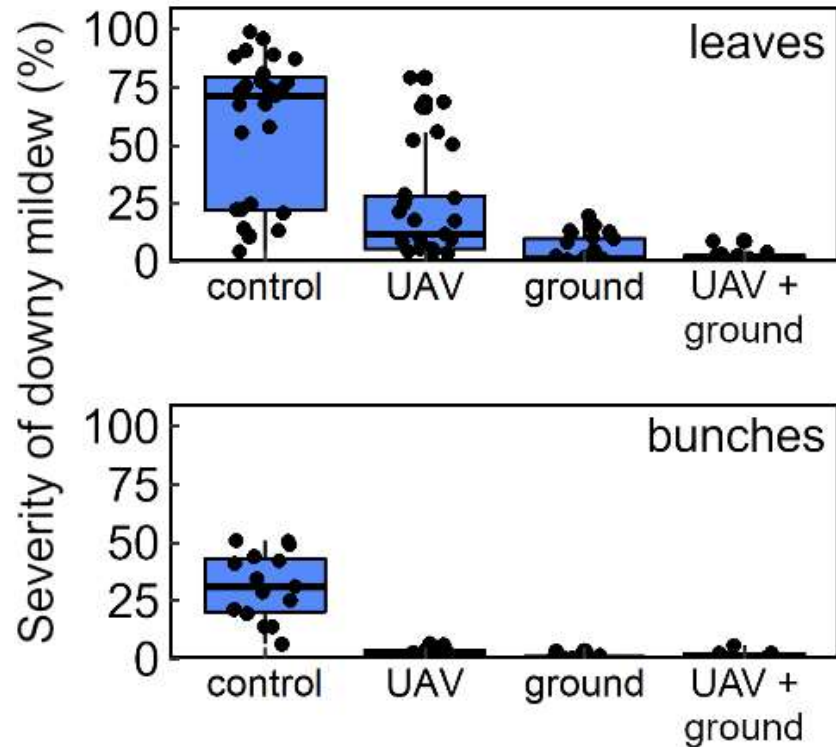
→ top leaves act like an umbrella

(Dubuis & Jaquero 2021)





# Efficacy of the treatments on vine



Control: no treatment

UAV: UAV treatments only

Ground: Standard treatments with air blast sprayer

UAV + ground: UAV in early stages, ground treatment for bunches

(Dubuis & Jaquero 2022)



# Conclusions

- drones found their place in vineyards with steep slopes
- homologation and sprayer tests work well since 5 years
- many positive echoes as hard, exposed work with knapsack sprayers can be replaced
- drones are replacing helicopters but not tractors
- limits in efficacy have to be well respected



**UAV sprayer in Switzerland**

Thomas Anken | Agroscope , Tänikon 1, CH-8356 Ettenhausen

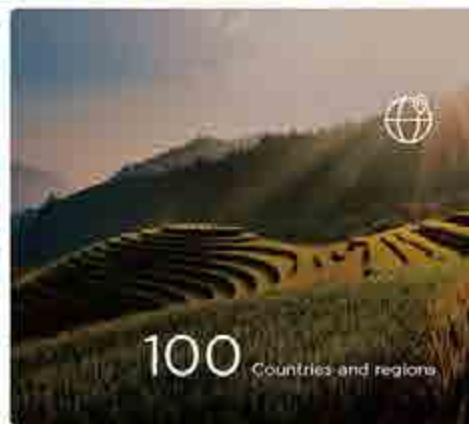
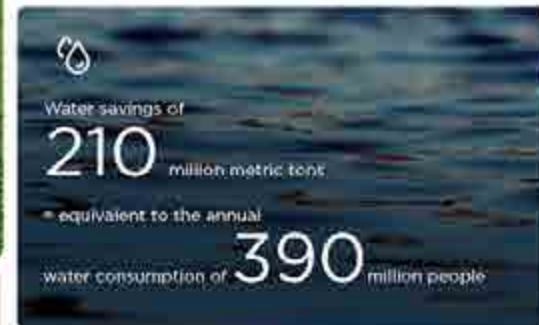


# UAV sprayers and drift measurements in Norway

Nils Bjugstad, REALTEK, NMBU

The 5th Agromek EurAgeng NjF Joint Seminar  
Herning 2024 11 26



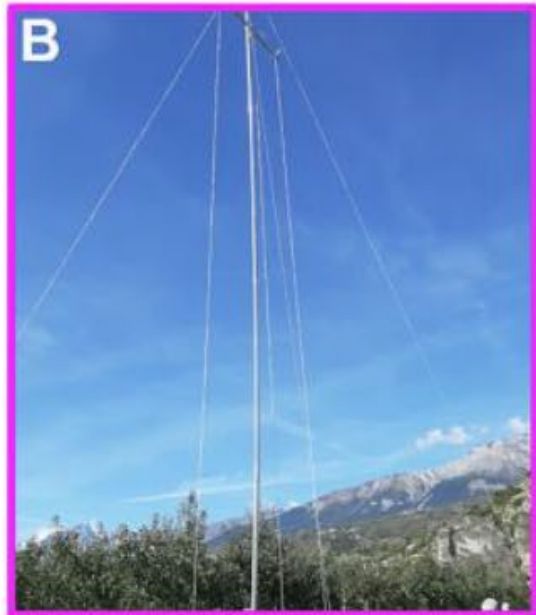




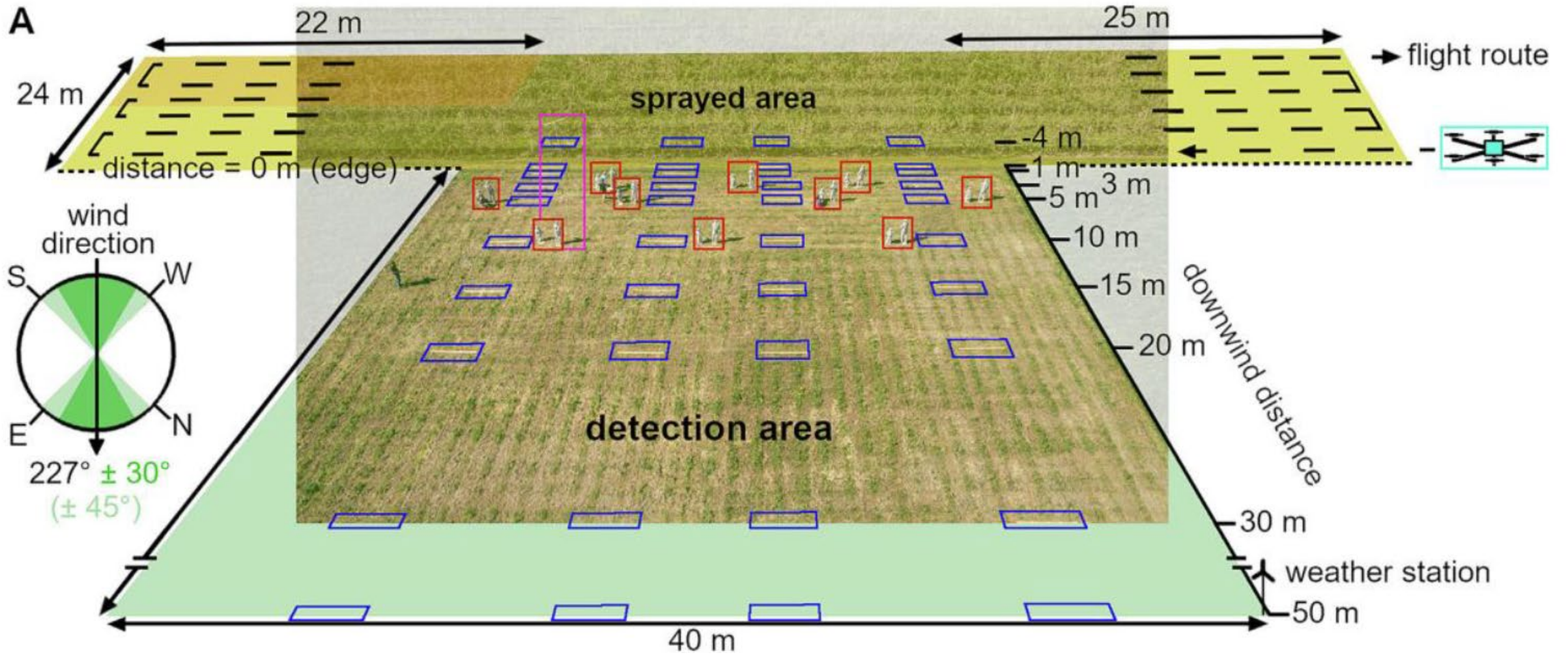
# UAV sprayers and possibilities in Norway

- Hilly areas
- Small fields
- What about quality of distribution
- Degree of drift hazard
- Capacity

# Several methods in use (ISO standards for drift measurements)







Dubuis et al, 2023

# Objectives

- Get a literature overview of methods of spray drift and in particular when using UAVs sprayers
- Evaluate possible methods for a pilot study measuring spray distribution and drift
- Perform some experiments with the most suitable method
- Evaluate the results due to distribution and spray drift by using this method



# Comparison of 3 methods to measure transversal distribution



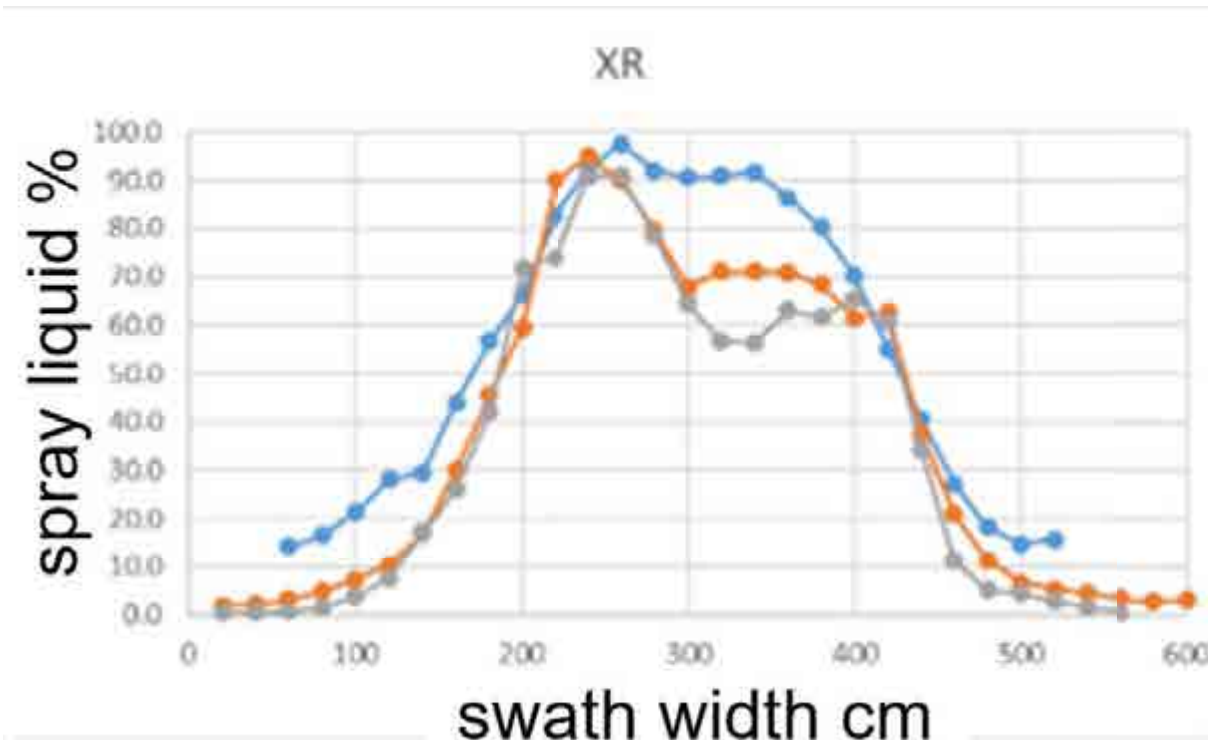
- patternator
- tracer and photometric analysis
- water sensitive paper: treated surface determined by computer vision

executed in collaboration with Syngenta



- yellow water sensitive paper
- white filter paper for tracer

# Transversal distribution of different nozzles and measuring methods



patternator

tracer

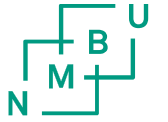
water sensitive paper

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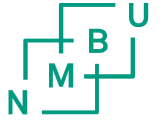
(Anken et al. 2024)



# Gobbler Swath Width Analyser



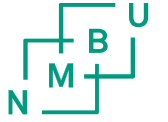
# Tested in Belgium (IVLO)



David Nuyttens, \_ILVO, Belgium, 2024



# Tested in Belgium (IVLO)



David Nuyttens, \_ILVO, Belgium, 2024

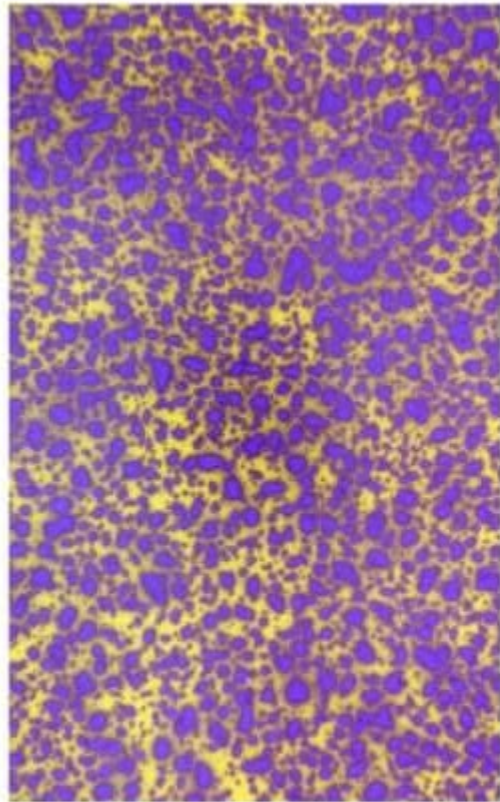
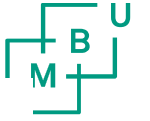
# Tests of different water sensitive paper



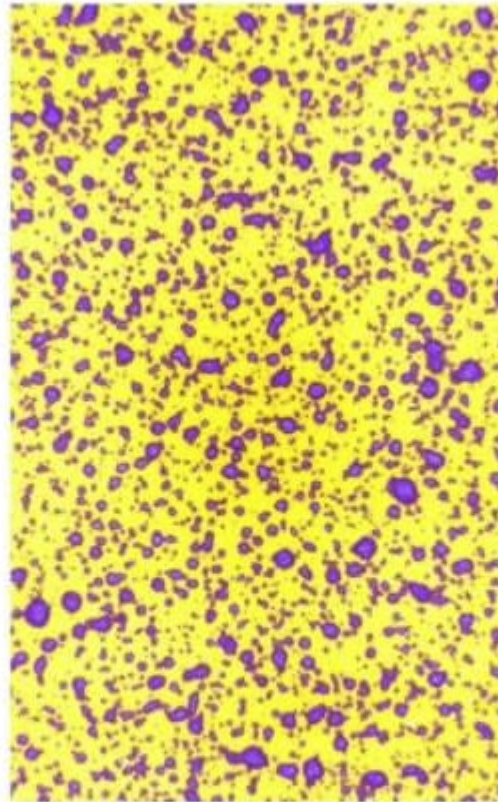
[www.sprayers101.com](http://www.sprayers101.com)



# Tests of different water sensitive paper

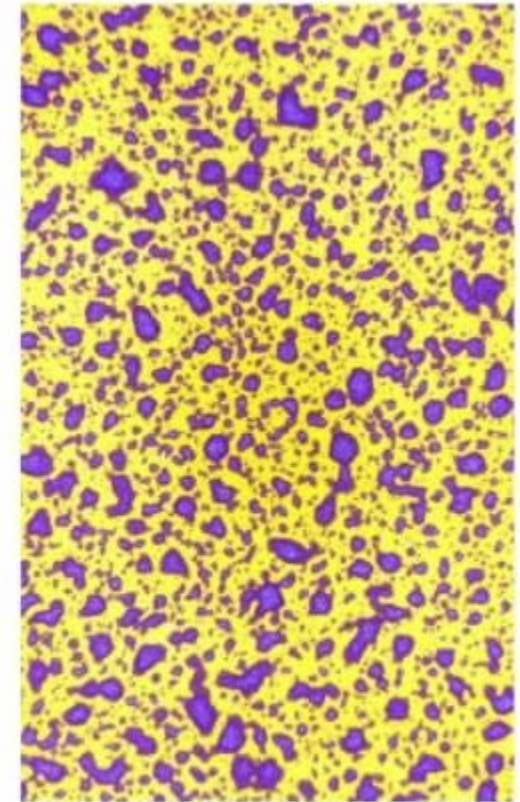


Syngenta



SpotOn

← Sprayed Simultaneously →



WSPaper

[www.sprayers101.com](http://www.sprayers101.com)

# Method used in our experiments

## Gobbler Swath analyser and paper roll

- Similar relative distribution of spray swath
- Quick method
- Possible to measure airborne drift?



Huge benefits compared with ISO drift measure methods



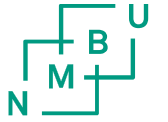
<b>Parameter</b>	<b>Drift hazard decreasing</b>	<b>Drift hazard increasing</b>
<b>Spray drone configuration</b>	<b>Nozzles correct to propellers</b>	<b>Nozzles outside propellers</b>
<b>Flight height</b>	<b>Low</b>	<b>High</b>
<b>Wind speed</b>	<b>Low</b>	<b>High (if possible &lt; 3 m/s)</b>
<b>Wind direction</b>	<b>Away from sensitive area</b>	<b>Against sensitive area</b>
<b>Forward speed</b>	<b>Low*</b>	<b>High</b>
<b>Drop size (nozzle, pressure)</b>	<b>No drops &lt; 100 µm</b>	<b>Large part &lt; 100 µm</b>
<b>Drop size range</b>	<b>Narrow span and &gt; 100 µm</b>	<b>Wide span and &lt; 100 µm</b>
<b>Additives</b>	<b>Suited additives</b>	<b>No additives</b>
<b>Vegetation type, size, density</b>	<b>A lot of vegetation filter effect</b>	<b>No vegetation</b>
<b>Drone weight</b>	<b>Heavy drone*</b>	<b>Light drone</b>
<b>Wash down</b>	<b>High air volume created*</b>	<b>Low air volume created</b>
<b>Distribution / spray picture</b>	<b>Ideal triangle picture</b>	<b>Poor distribution profile</b>
<b>Temperature</b>	<b>Low temperature</b>	<b>High temperature</b>
<b>RH</b>	<b>High RH</b>	<b>Low RH</b>
<b>Volume rate</b>	<b>High volume rate</b>	<b>Low volume rate</b>
<b>Terrain type and variation</b>	<b>Even and easy terrain</b>	<b>Huge variations</b>
<b>Tilting of drone</b>	<b>No tilting</b>	<b>Huge degree of tilting</b>

# Layout of paper roll (distribution and airborne drift)





# Layout of paper roll (distribution and airborne drift)





# Layout of paper roll (distribution and airborne drift)

